

TASK

Implement estimation of the following non-linear regression model using a fast and stable algorithm:

$$Y = \text{Beta1} * (1 - 1 / \text{sqrt}(1 + 2 * \text{Beta2} * X)) + \text{Epsilon}.$$

SOLUTION

The Matlab code is displayed below.

```
function [Beta, RSS, SigmaSq, CovarianceOfBeta, StandardErrors, Iter] =
NonLinearRegression(Y,X,InitialBeta)

% This function implements an iterative procedure for estimating a
% non-linear regression model of the form:
%
% Y = h(X,Beta) + Epsilon,          (*)
%
% where X and Y are random variables, Beta = (Beta1, Beta2) and
%
% h(X,Beta) = Beta1 * (1 - 1 / sqrt( 1 + 2*Beta2*X ) ).
%
% The iterative procedure is based on LINEARIZATION of equation (*) by
% applying Taylor expansion to function h(X,Beta) and running Ordinary
% Least Squares (OLS) for the resulting linear regression. Here is how
% linearization works:
%
% 1] Choose reasonable possible value for Beta = (Beta1, Beta2). This will
% be our Beta_0.
%
% 2] Treat h(X,Beta) as a function of Beta and write down a first-order
% Taylor approximation for h(X,Beta) in the neighborhood of Beta_0.
% Substitute the approximation into equation (*). Now the right hand side
% is a linear function of Beta. Therefore Beta can be estimated using methods
% for linear regression.
%
% 3] Estimate Beta by OLS. Let Beta_Hat be our estimate.
%
% 4] If Beta_Hat is within tolerance from Beta_0, choose Beta_Hat as the
% final estimate of coefficients Beta. Otherwise, set Beta_0 to Beta_Hat
% and go to the step 2.
%
% The substantiation of this iterative procedure is well explained in
% Greene, "Econometric Analysis", Ch. "Nonlinear Regression Models".

%
%
% This ensures that X and Y are column vectors.
Size      = size(Y);
if Size(2) > 1
    Y = Y';
end
Size      = size(X);
if Size(2) > 1
    X = X';
end
```

```

% Initialization.
Tolerance = 1e-6;
Discrepancy = 100;
Iter = 0;
Beta = InitialBeta';

while Discrepancy > Tolerance
    % Update the number of iterations.
    Iter = Iter+1;

    % hfun evaluated at the initial values:
    h0 = Beta(1) * (1 - 1 ./ sqrt( 1 + 2*Beta(2)*X ));

    % Need pseudoregressors at the initial values
    x1_0 = 1 - 1 ./ sqrt( 1 + 2*Beta(2)*X );
    x2_0 = Beta(1)*X .* ( 1 + 2*Beta(2)*X ).^(-3/2);

    % Collect them in our pseudoregressors matrix
    X0 = [x1_0 x2_0];

    % Now compute X0Beta0
    h0_delta = X0*Beta;

    % We're now ready to compute the new dependent variable
    y0 = Y - h0 + h0_delta;

    % We can estimate our linearized model with OLS
    NewBeta = regress(y0,X0);

    % Check improvement
    Discrepancy = max(abs((Beta-NewBeta) ./ InitialBeta'));

    % Update the coefficients.
    Beta = NewBeta;
end

% Calculating various statistics to be able to produce the covariance
% matrix of the coefficients estimates.
N = length(Y);
K = 2;
Fit = Beta(1) * (1 - 1 ./ sqrt( 1 + 2*Beta(2)*X ));
RSS = sum( (Y - Fit).^2 );
SigmaSq = 1/(N - K) * RSS;

% Need pseudoregressors at the initial values
x1_0 = 1 - 1 ./ sqrt( 1 + 2*Beta(2)*X );
x2_0 = Beta(1)*X .* ( 1 + 2*Beta(2)*X ).^(-3/2);
X0 = [x1_0 x2_0];

CovarianceOfBeta = inv(X0'*X0) * SigmaSq;
StandardErrors = [sqrt(CovarianceOfBeta(1,1)),
sqrt(CovarianceOfBeta(2,2))];

```

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